

$$\begin{array}{llll}
\vec{F}_{net} = m\vec{a} & \Delta\theta = \theta - \theta_0 & \Delta\omega = \omega - \omega_0 & s = r\theta \\
\vec{v} = \frac{d\vec{r}}{dt} & \vec{a} = \frac{d\vec{v}}{dt} & \vec{r} = \vec{r}_0 + \vec{v}_0 t + \frac{1}{2}\vec{a}t^2 & v^2 = v_0^2 + 2\vec{a} \cdot (\vec{r} - \vec{r}_0) \quad v = r\omega \\
\omega_{avg} = \frac{\Delta\theta}{\Delta t} & \alpha_{avg} = \frac{\Delta\omega}{\Delta t} & x = x_0 + v_{0x}t + \frac{1}{2}a_x t^2 & v_x^2 = v_{0x}^2 + 2a_x(x - x_0) \quad a_t = \frac{dv_t}{dt} = r\alpha \\
\omega = \frac{d\theta}{dt} & \alpha = \frac{d\omega}{dt} = \frac{d^2\theta}{dt^2} & \theta = \theta_0 + \omega_0 t + \frac{1}{2}\alpha t^2 & \omega^2 = \omega_0^2 + 2\alpha(\theta - \theta_0) \quad a_r = \frac{v_t^2}{r} = \omega^2 r \\
I = \sum_i m_i r_i^2 & I = \int_{\text{rigid body}} r^2 dm & I = I_{com} + Mh^2 & W = \int_{\theta_i}^{\theta_f} \tau d\theta \quad K_{final} + U_{final} = K_{initial} + U_{initial} + W_{nonconservative}
\end{array}$$

$$\begin{array}{llll}
\vec{\tau} = \vec{r} \times \vec{F} & \tau = rF \sin\theta = rF_{\perp} = r_{\perp}F & \tau_{net} = I\alpha & K = \frac{1}{2}I\omega^2 \quad P = \tau\omega \quad W_{total} = K_{final} - K_{initial} \\
v_{com} = \omega r & \vec{\ell} = \vec{r} \times \vec{p} = \vec{r} \times m\vec{v} & \vec{L} = \sum \vec{\ell} & \vec{\tau}_{net} = \frac{d\vec{L}}{dt} \quad \frac{F}{A} = E \frac{\Delta L}{L}
\end{array}$$

$$\begin{array}{llll}
a_{com} = \alpha r & \ell = rp \sin\phi = rp_{\perp} = r_{\perp}p & L_z = I\omega_z & \frac{F}{A} = G \frac{\Delta x}{L} \quad p = B \frac{|\Delta V|}{V} \\
F = -kx & f = \frac{1}{T} = \frac{\omega}{2\pi} & a(t) = -\omega^2 x(t) & x(t) = x_m \cos(\omega t + \phi) \quad U = \frac{1}{2}kx^2
\end{array}$$

$$\begin{array}{llll}
T = 2\pi\sqrt{\frac{m}{k}} & T = 2\pi\sqrt{\frac{I}{mgh}} & y(x,t) = h(x \pm vt) & y(x,t) = y_m \sin(kx \pm \omega t + \phi) \quad v = \lambda f = \frac{\omega}{k} \quad k = \frac{2\pi}{\lambda}
\end{array}$$

$$v = \sqrt{\frac{F_T}{\mu}} \quad P_{avg} = \frac{1}{2}\mu v \omega^2 y_m^2 \quad y(x,t) = 2y_m \sin(kx) \cos(\omega t) \quad f_n = n f_1; \lambda_n = \frac{2L}{n}; n = 1, 2, 3, 4, 5, \dots$$

$$\begin{array}{llll}
y(x,t) = 2y_m \cos\left(\frac{\phi}{2}\right) \sin\left(kx - \omega t - \frac{\phi}{2}\right) & \frac{\phi}{2\pi} = \frac{\Delta L}{\lambda} & I = \frac{P}{A} & I = \frac{P}{4\pi r^2} \quad I = \frac{1}{2}\rho v \omega^2 s_m^2 \quad v = \sqrt{\frac{B}{\rho}}
\end{array}$$

$$\Delta p(x,t) = \Delta p_{max} \sin(kx - \omega t) \quad s(x,t) = s_{max} \cos(kx - \omega t) \quad \Delta p_{max} = \rho v \omega s_m$$

$$\beta = 10 \text{ dB} \log \frac{I}{I_0} \quad I_0 = 10^{-12} \frac{\text{W}}{\text{m}^2} \quad f' = f \frac{v \pm v_D}{v \pm v_s}$$

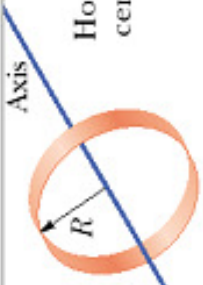
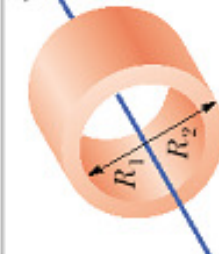
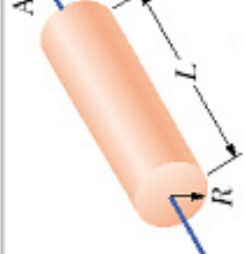
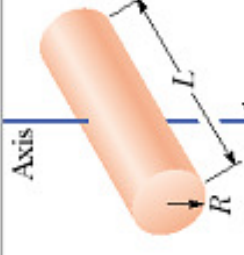
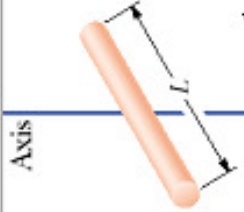
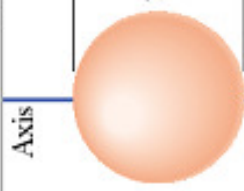
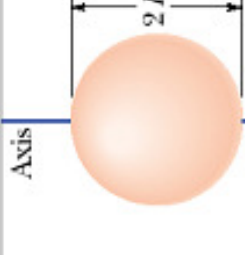
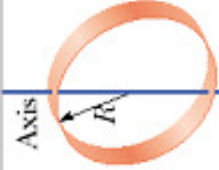
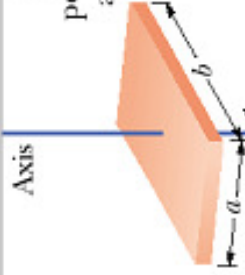
$$y(x,t) = 2y_m \cos\left(\frac{\Delta k}{2}x - \frac{\Delta\omega}{2}t\right) \sin(k_{avg}x - \omega_{avg}t) \quad f_{beat} = |f_2 - f_1|$$

$$n = \frac{c}{v} \quad n_1 \sin\theta_1 = n_2 \sin\theta_2 \quad \frac{1}{f} = \frac{1}{p} + \frac{1}{i} \quad m = -\frac{i}{p} \quad m = \frac{h'}{h}$$

$$d \sin\theta = m\lambda \quad m = 0, \pm 1, \pm 2, \dots \text{ (constructive)} \quad I = 4I_0 [\cos(\phi/2)]^2 \quad \phi = \frac{2\pi d}{\lambda} \sin\theta$$

$$a \sin\theta = m\lambda \quad m = \pm 1, \pm 2, \pm 3, \dots \text{ (destructive)} \quad I = I_m \left[\frac{\sin(\phi/2)}{\phi/2} \right]^2 \quad \phi = \frac{2\pi a}{\lambda} \sin\theta$$

$$\tan\theta_B = \frac{n_2}{n_1} \quad I = I_0 \cos^2\theta$$

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|--|--|--|
|  <p>Hoop about central axis</p> $I = MR^2$ <p>(a)</p> |  <p>Annular cylinder (or ring) about central axis</p> $I = \frac{1}{2}M(R_1^2 + R_2^2)$ <p>(b)</p> |  <p>Solid cylinder (or disk) about central axis</p> $I = \frac{1}{2}MR^2$ <p>(c)</p> |
|  <p>Solid cylinder (or disk) about central diameter</p> $I = \frac{1}{4}MR^2 + \frac{1}{12}ML^2$ <p>(d)</p> |  <p>Thin rod about axis through center perpendicular to length</p> $I = \frac{1}{12}ML^2$ <p>(e)</p> |  <p>Solid sphere about any diameter</p> $I = \frac{2}{5}MR^2$ <p>(f)</p> |
|  <p>Thin spherical shell about any diameter</p> $I = \frac{2}{3}MR^2$ <p>(g)</p> |  <p>Hoop about any diameter</p> $I = \frac{1}{2}MR^2$ <p>(h)</p> |  <p>Slab about perpendicular axis through center</p> $I = \frac{1}{12}M(a^2 + b^2)$ <p>(i)</p> |